REMOTE GSM SWITCH GRM-10

MANUAL INSTRUCTION

za/el



DESCRIPTION

The GRM-10 device is designed to realise simple control and notice operations. The operations are carried out by means of the GSM network. The controller has two independent outputs with a maximum load capacity of 16 A / 250 V AC. Two digital inputs allow for a link with the alarm control panels. The RS485 interface in connection with the RXM-01 translator gives a possibility to control EXTA FREE system receivers with the help of a mobile phone and messages that are defined by the user. The number of operation modes and configuration options make the GRM-10 a very useful device for simple home automation and industrial systems. The GRM-10 device is made in a three-MOD casing and is designed for mounting in switchboards on a TH35 rail

FEATURES

- Remote control of the electrical devices by means of commands (incoming phone connection, text message) sent from a mobile phone,
- Comfortable control of difficult access devices (air conditioning, heating, etc.),
- Two relay outputs with the load capacity of 16 A,
- Operation is optically signalled (power supply, relay status, GSM modem status)
- Low power consumption, a possibility of continuous operation.

The device is designed for singlephase installation and must be installed in accordance with standards valid in a particular country. The device should be connected according to the details included in this operating manual. Installation, connection and control should be carried out by a qualified electrician staff, who act in accordance with the service manual and the device functions. In case of casing dismantling an electric shock may occur, and the guarantee is lost then. Before installation make sure the connection cables are not under voltage. The cruciform head screwdriver 3,5 mm should be used to instal the device influence its wrong functioning. It is not advisable to instal the device in the following cases: if any device part is missing or the device is damaged or deformed. In case of improper functioning of the device contact the producer.



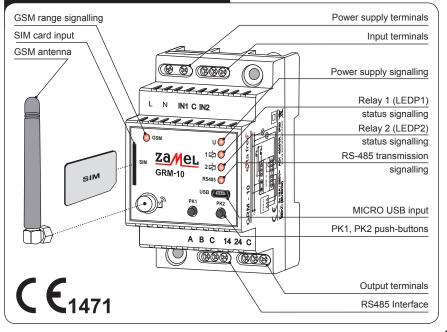
The symbol means selective collecting of electrical and electronic equipment. It is forbidden to put the used equipment together with other waste. ZAMEL Sp. z o.o.

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TECHNICAL PARAMETERS

GRM	1-10
Nominal input rated voltage:	230 V AC 50 / 60 Hz
Input voltage tolerance:	-15 ÷ +10 %
Nominal power consumption:	1,5 W
GSM frequency:	900/1800/1900 MHz
Operating range:	restricted by the GSM network
Supply voltage optical signalling:	LED diode (green)
GSM status signalling:	LED diode (yellow)
Output number:	2
Output status signalling:	2 x LED diode
Output relays parameters:	2 x NO 16 A / 250 V AC AC1 4000 VA
Input number:	2
Input type:	Digital - potential +4 V
Interfaces:	RS485 MODBUS - A,B,C terminals; USB; PK1, PK2 push-buttons
RS485 transmission signalling:	LED diode
Position on RS485 bus:	only MASTER
Ambient temperature range:	-10 ÷ +55 °C
Operating position:	free
Casing mounting:	TH35 rail
Casing protection degree:	IP20 (PN-EN 60529)
Protection class:	П
Overvoltage category:	П
Pollution degree:	2
Dimensions:	3-modular casing
Weight:	163 g
Reference standard:	PN-EN 60950-1:2007; PN-EN 55024:2000; PN-EN 61000-4-4

APPEARANCE



SOFTWARE UPGRADE

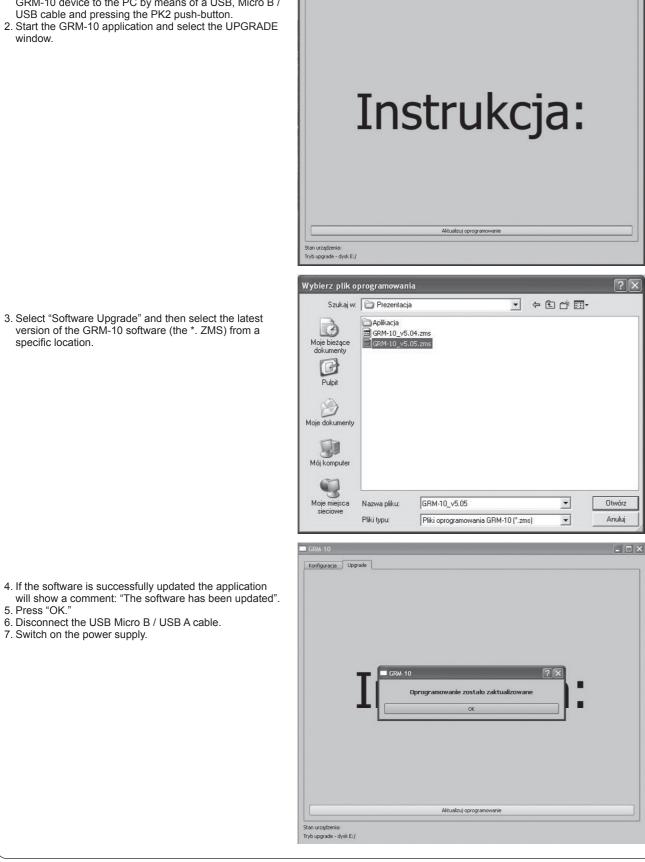
The GRM-10 user has the ability to upgrade the software using the Micro USB interface. It may be necessary in case of an upgrade release by the producer. Information on the current software can be found on the product website http://www.zamelcet.com/pl,263,4537,sterownik gsm modulowy 2kanalowy grm10.html

GRM-10

Konfiguracja Upgrade

The upgrade is carried out by the GRM-10 application on the PC:

- 1. After switching off the power supply voltage connect the GRM-10 device to the PC by means of a USB, Micro B / USB cable and pressing the PK2 push-button.
- 2. Start the GRM-10 application and select the UPGRADE window



CONNECTION AND INSTALLING DIAGRAM LØ NØ -0 0-____ ৫ ৫ ৫ ৫ ৫ \otimes IN1 C IN2 GRM-10 \otimes A B C 14 24 C $\overline{Q}\overline{Q}\overline{Q}\overline{Q}\overline{Q}\overline{Q}\overline{Q}\overline{Q}\overline{Q}$

DEVICE CONFIGURATION

GRM-10 has a default factory settings. Before use, carefully read the manual instruction and make a proper device configuration. In order to freely manage the configuration settings, the GRM-10 device makes the local and remote configuration possible. The remote configuration allows to manage the settings of the already working GRM-10 device without a physical access to it (for example, to a device that is installed in the building). The configuration can be done as follows: a) by means of a mobile phone via text massage (local and remote configuration), b) by means of the PC application via the Micro USB interface (only the local configuration).

Local configuration by means of a mobile phone

- 1. Press the PK2 push-button on the front panel.
- 2. Switch on the power supply and keep the PK2 push-button pressed.
- 3. Hold the PK2 push-button as long as the LED red diodes LEDP1 and LEDP2 start flashing.
- 4. Wait until the GRM-10 device logs into the GSM network (LED yellow diode GSM flashes).
- 6. Switch off the power supply from the mains.

Remote configuration by means of a mobile phone

The remote configuration is available only for these telephone numbers that have been added to the so called administrative numbers' list by means of the configuration command ADMIN (see CONFIGURATION COMMANDS) during the local configuration (by means of a text message or a PC application). The remote configuration is possible during a usual device operation if it is "logged in" to the GSM network. 1. Send a text message with a CONFIG MODE content from a telephone number included on the ADMIN list.

- 2. By receiving the above text message, the GRM-10 device will send back a reply "CONFIG MODE OK' and will enter the configuration mode, which is indicated by flashing red LED diodes LEDP1 and LEDP2.
- 3. Carry out the device configuration in accordance with the CONFIGURATION COMMANDS. 4. Send a TEXT MESSAGE with the CONFIG MODE END content to leave the remote configuration mode.
- 5. By receiving the above text message, the GRM-10 device will send back a reply "CONFIG" MODE END -OK' and will enter a usual operation mode

When entering / leaving the remote configuration mode, the outputs' status remains unchanged.

Configuration by means of the PC application via an MIC RO USB interface

NOTE: Every time before making any changes in the configuration settings by means of the PC application, first read the current configuration of the GRM-10 device. It is necessary not to overwrite or lose the configuration settings implicated by the telephone text message. 1. Start the GRM-10 application on PC.

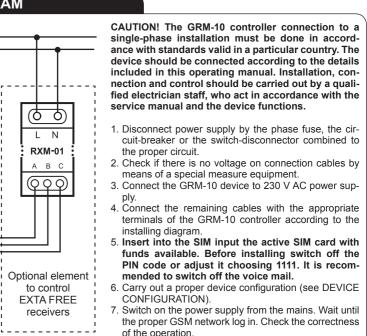
- 2. Switch off the power supply to connect the MICRO USB to the GRM-10 device.
- 3. Wait until the GRM-10 device appears in the operating system to install properly.
- 4. READ CURRENT GRM-10 DEVICE CONFIGURATION.
- 5. Carry out / change the configuration adjustments by means of the PC application.
- 6. In order to save the current configuration of the GRM-10 device, press the "ZAPISZ DO URZĄDZENIA" push-button.
- TION ERROR' displays.
- 9. Disconnect the MICRO USB cable from the GRM-10 device.

Saving the configuration to *. zml file

The current configuration can be saved to a '*.zml' file. In order to do it, by means of the application press the "ZAPISZ DO PLIKU' pushbutton and select the proper file place to save it.

Reading the configuration from the *. zml file

The current configuration can be read from the '*.zml' file. In order to do it, by means of the application press the "WCZYTAJ Z PLIKU" push-button, next choose the correct file place to read it.



5. Adjust the configuration parameters by sending appropriate text messages (see CONFIGURATION COMMANDS).

7. Press shortly the PK1 push-button on the front panel of the GRM-10 device (LED yellow diode RS485 switches on for a moment). 8. If the configuration is correct, the application sends back a message 'CONFIGURATION OK.' Otherwise the message 'CONFIGURA-

DEV	ICE	CON	NTRO	DL

Type of control	Possible control types	Remarks
By means of PK1 / PK2 push buttons on	Bistable ON/OFFTime TIMEGate GATE	• Times for TIME and GATE modes are adjusted during con- figuration.
By calling to the device	 Bistable ON/OFF Time TIME Gate GATE 	 Times for TIME and GATE modes are adjusted during configuration. The number of signals specified during configuration (in ON / OFF and TIME modes the user must disconnect after certain number of signals, in the GATE mode the disconnection is automatical.
By sending a specified message with a control command to the device	 Bistable ON/OFF Time TIME Gate GATE EXTA FREE control 	• Times for the TIME and GATE modes are adjusted during configuration with a possibility of changing the text in the control text message.

* ON / OFF bistable mode - change of the CH1 or CH2 output status to the opposite.

TIME time mode - change of the CH1 or CH2 output status to the opposite and appropriately through time t1 for CH1 output and time t2 for CH2 output

GATE gate mode - change of the CH1 and / or CH2 into times defined for the gate mode.

EXTA FREE control - control of EXTA FREE system wireless receivers by means of RXM-01 device RXM-01 connected with the GRM-10 device.

CONFIGURATION COMMANDS

Command	Description
CONFIG	 Configuration of telephone numbers authorized to control the CLIP. Configuration of the optional password for controlling text messages. Configuration of confirmation.
CONFIG MODE	Adjusting the device for the remote configuration mode.
CONFIG MODE END	Deleting the remote configuration mode.
ADD NUM	Entering additional phone numbers to the list of numbers authorised to control the CLIP. By means of one commend maximum six numbers can be added every time. Applies to local and remote configuration
DEL NUM	• Deleting a number (s) from the list of telephone numbers authorized to control the CLIP. Every time by means of one command up to six numbers may be deleted. It refers to local and remote configuration.
ADMIN	Configuration of telephone numbers authorized to a remote configuration.
INFO	Configuration of telephone numbers the text messages will be sent to (it refers to the outputs' status and occurrences on IN1, IN2 inputs).
RELAY1	 Operation mode configuration for CH1 output. Operation mode configuration of CH1 output after power supply voltage is switched off.
RELAY2	 Operation mode configuration for CH2 output. Operation mode configuration of CH2 output after power supply voltage is switched off.
MODBUSCONFIG	Configuration of RS485 transmission parameters for MODBUS protocol.
GATE	Gate mode configuration.
TASK IN1	IN1 input configuration.
TASK IN2	IN2 input configuration.
EF	Control command configuration for EXTA FREE system.
EF RESET	Deleting the control command table for EXTA FREE system.
RESET CONFIG	Restore the default settings (it does not refer to EXTA FREE commands).

CONFIGURATION MODE COMMAND

The command makes the GRM-10 device enters from the normal operation mode into the remote configuration mode. The active command is only for the numbers included in the ADMIN list (by means of ADMIN command or the PC application). The enter into the configuration mode is indicated by a flashing LED diodes LEDP1 and LEDP2.

CONFIGURATION MODE END COMMAND

The command allows the the GRM-10 device to go out from the configuration mode to normal operation. The active command is only for the numbers included in the ADMIN list (by means of ADMIN command or the PC application). The command is inactive during local configuration

CONFIG COMMAND

The maximum of numbers available n = 6

- message. No parameter means a free access for any number during text message control.
- ACK Keyword it specifies whether the GRM-10 device must send a confirming text message every time after a specified command is realised:
 - REL1 confirmation only for CH1 channel
 - **REL2** confirmation only for CH2 channel
 - REL12 confirmation for channels CH1 and CH2
 - No parameter means no confirmation for channels CH1 and CH2 <>

Examples of commands

CONFIG +48602360938 +48600915257

Command

CONFIG +48602360938 +48600915257 ACK REL1

CONFIG +48602360938 +48600915257 ACK REL2

CONFIG +48602360938 +48600915257 ACK REL12

Numbers +48602360938, +48600915257 globally released to CONFIG +48602360938 +48600915257 PASS ZAMEL ACK REL1 | control CLIP, ZAMEL password for text message control, confirmations only for OUT1 output.

NOTE: If there is a need to add more authorised numbers to control the CLIP (including control in the gate mode) it can be done by means of the PC application (telephone section) or the ADD NUM command in configuration mode. It is possible to enter up to 500 numbers. In order to delete the selected telephone number, use the PC application or the DEL NUM command in configuration mode.

ADD NUM COMMAND

The command adds a telephone number / numbers to the authorised list of numbers used to control CLIP (including the control in the gate mode). 6 telephone numbers maximally can be added by one command at each time. The command refers to the local and remote configuration.

ADD NUM <+48tel 1> <+48tel 2>,...,<+48tel n>

tel 1...tel n successively entered phone numbers preceded by +48 The maximum of numbers available n = 6.

Examples of commands

Command

ADD NUM +48602360938

ADD NUM+48603360928 +48600915257 +48600500800

DEL NUM COMMAND

The command deletes a telephone number / numbers from the authorised list of numbers used to control CLIP (including the control in the gate mode). 6 telephone numbers maximally can be deleted by one command at each time. The command refers to the local and remote configuration.

DEL NUM <+48tel 1> <+48tel 2>,...,<+48tel n>

tel 1...tel n successively entered phone numbers preceded by +48. The maximum of numbers available n = 6.

Examples of commands

Command

DEL NUM +48602360938

DEL NUM+48603360928 +48600915257 +48600500800

CONFIG <+48tel_1> <+48tel_n> PASS <password from 5 to 8 signs> ACK <REL1,REL2, REL12>

PASS Keyword - it specifies the password added to the text message during control. The password is added at the beginning of the

Description

Numbers +48602360938. +48600915257 globally released to control CLIP, no password for text message control, no confirmations for OUT1 and OUT2 outputs.

Numbers +48602360938, +48600915257 globally released to control CLIP, no password for text message control, confirmations only for OUT1 output.

Numbers +48602360938, +48600915257 globally released to control CLIP, no password for text message control, confirmations only for OUT2 output.

Numbers +48602360938, +48600915257 globally released to control CLIP, no password for text message control, confirmations for OUT1 and OUT2 outputs.

Description

Number +48602360938 is added to the authorised list of numbers used to control by means of CLIP calling signals.

Numbers +48603360928 +48600915257 +48600500800 are added to the authorised list of numbers used to control by means of CLIP calling signals.

Description

Number +48602360938 is deleted from the authorised list of numbers used to control by means of CLIP calling signals

Numbers +48603360928 +48600915257 +48600500800 are deleted from the authorised list of numbers used to control by means of CLIP calling signals.

INFO COMMAND

INFO <+48tel_1> <+48tel_2>,...,<+48tel_n>

tel 1...tel n successively entered phone numbers preceded by +48. The text messages will be sent to these numbers. The confirmations refer to the changed output status and occurences on IN1. IN2 inputs.

The maximum of numbers available n = 6

The confirming text messages are sent only if the ACK parameter is set in the CONFIG command. Sending the INFO command with new telephone numbers results in deleting the previous numbers and writing the new ones.

Examples of commands:

Command	Description	
INFO +48602360938 +48600915257	Text messages will be sent to the following numbers +48602360938, +48600915257 confirming the realization of a specified control command or occurences on inputs.	
INFO +48602360938 +48600915257 +48600500800	Text messages will be sent to the following numbers +48602360938, +48600915257, +48600500800 confirming the realization of a specified control command or occurences on inputs.	

RELAY1 / RELAY 2 COMMAND

RELAY1 <ON/OFF/MEM> <mode> <t1> RING <y> RELAY2 <ON/OFF/MEM> <mode> <t2> RING <v>

<ON/OFF/MEM> The parameter defines the output status OUT1/OUT2 after switching on power supply from the mains:

- ON Output switched on.
- OFF Output switched off.
- MEM GRM-10 remembers the output status when the power supply is switched off and then switched on again, the output has the same status as it was before the power supply switch off. The parameter is not adjusted for the TIME mode.
- <mode> A parameter that defines the operating mode of OUT1/OUT2 outputs it is default for CLIP control.
- ONOFF Bistable mode (Switch on / switch off).
- TIME Time mode
- <t1>/<t2> A parameter that defines default times [s] for the time mode possible value from 1 to 3600 RING A keyword defining the number of ring signals to control CLIP.
 - <y> A parameter defining the number of rings to control CLIP. The parameter is adjusted in the range of 2 to 12.

If the RING keyword and <v> parameter is not adjusted, the control is carried out only by sending text messages. OUT1/OUT2 outputs are independently configurable.

Examples of commands:

Command	Description
RELAY1 ON ONOFF RING 3	OUT1 output is switched on, bistable mode, adjustment after three rings.
RELAY1 MEM ONOFF RING 2	OUT1 output in the status before power supply switch off, bistable mode, activation after two rings
RELAY1 OFF TIME 60 RING 4	OUT1 output is switched off, time mode, time 60 seconds, adjustment after 4 rings
RELAY2 OFF ONOFF	OUT2 output is switched off, bistable mode, control only by means of text mes- sage
RELAY2 ON TIME 10 RING 2	OUT2 output is switched on, time mode, time 10 seconds, adjustment after 2 rings

MODBUSCONFIG COMMAND

Default MODBUS protocol configuration in GRM-10 device allows for a direct connection with EXTA FREE translator / RS-485 RXM-01 type. GRM-10 device in such a connection is only a MASTER on the MODBUS bus - it receives control text messages and by means of RS-485 bus it sends appropriate commands to the RXM-01 device. A default configuration

Protocol: MODBUS RTU 8 bits of data Parity: Parity bit + stop bit Transmission rate: 9600 kbps Address on the bus: 0x01 MODBUSCONFIG <address> <rate> PARITY <parity options> <address> A parameter defining address on the bus: 1...247. <rate> A parameter defining transmission rate on the RS-485 bus: 2400 - 2400 kbps. 4800 - 4800 kbps. 9600 - 9600 kbps, 19200 - 19200 kbps PARITY A keyword defining parity options. Selection possibilities NO – no parity ODD - odd test

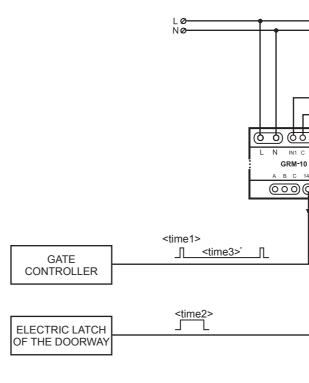
EVEN - parity test. Examples of commands Command Description MODBUSCONFIG 1 9600 PARITY EVEN Address 0x01, transmission rate 9600kbps, parity test MODBUSCONFIG 1 2400 PARITY ODD Address 0x01, transmission rate 2400kbps, odd test

GATE COMMAND (GATE MODE)

In the gate mode the settings are as follow: OUT1 - it cooperates with the existing gate controller that controls the gateway. OUT2 - it cooperates with the electric latch opening the entry gate to the possession. The number of telephones authorized to control in the gate mode by means of a ring (CLIP) are adjusted in the CONFIG configuration mode (up to 6 numbers) or by means of: • the ADD NUM command in the configuration mode, • the PC application in the Telephones section / CLIP (up to 500 numbers) in the configuration mode. GATE <TIME 1> <TIME2> RING <y> AUTO <TIME3> <TIME 1> A parameter that defines the default time [s] of the OUT1 output - configurable in the range of 0 to 10. OUT1 task is to generate a pulse to the gateway controller. If this parameter is set to "0", then OUT1 output is inactive. <TIME 2> A parameter that defines the default time [s] of the OUT2 output - configurable from 0 to 360. The OUT2 output task is to provide voltage supply to the electric latch. If this parameter is set to "0", then the OUT2 output is inactive RING A keyword that defines the number of rings to control outputs in the gate mode by means of a CLIP. <y> A parameter that defines the number of rings to control outputs in the gate mode by means of a CLIP. This parameter is configured in the range of 2 to 6. If it is not set, the control is carried out only by means of text messages. AUTO A keyword to configure the AUTO mode. In the AUTO mode, after <TIME 3> finishes a gate controller's pulse is automatically generated for a defined <TIME1> time. This impulse is to automatically close the door. If the AUTO mode is activated, the gate remains open till the GATE command is activated, till the next "CLIP'a", till the next pulse in IN1 input or till another pressing of the PK1 push-button. <TIME3> A parameter that defines the time [s] during which the gate remains open. The time is measured after <TIME1> finishes. It is configured in the range from 1 to 600. While adjusting <TIME3> it is necessary to take into consideration the time taken to open the gate IN1/IN2 inputs are not configurated in the gate mode. The inputs have the following default settings: • The appearance of a short pulse in the IN1 input results in switching on the OUT1 output for the time <TIME1> that is adjusted during the gate mode configuration. • The appearance of a short pulse in the IN2 input results in switching on the OUT2 output for the time <TIME2> that is adjusted during the gate mode configuration ... Description time2 = 15 s, setting the CLIP after 2 rings time2 = 10 s, setting the CLIP after 2 rings, automatically generatclose the gate after time3 = 350 s time2 = 100 s, control only by means of tex messages ration only to open the doorway (latch operation time = 60 s) ration only to open the gate (pulse time = 2 s) Manual control of the gateway П 59699 Manual control IN1 C IN GRM-10 of the doorway 000000 <time1> <time3>* П GATE CONTROLLER

Examples of commands:

Command	
GATE 2 15 RING 2	time1 = 2 s,
GATE 2 10 RING 2 AUTO 350	time1 = 2 s, ing pulse to
GATE 2 100	time1 = 2 s,
GATE 0 60	Pulse gener
GATE 2 0	Pulse gener



The GRM-10 connection diagram in the gate mode

* if the parameter AUTO is set

	N/OFF> or TASK IN2 <lo hi=""> RELAY2 <on off=""> ME <t1> or TASK IN2 <lo hi=""> RELAY2 TIME <t2></t2></lo></t1></on></lo>
	> NONE or TASK IN2 <lo hi=""> NONE</lo>
TASKI IN1/TASK IN2 – defines the output the configura RELAY1/RELAY2 – defines the output that must be acti	vated after a given status occurance in the input
limited by $ $ parameters.	 status in IN1 / IN2 input, the OUT1/OUT2 output changes its status for a till
NONE – defines that after an occurrence of the <lo hi<br="">spond).</lo>	> status in IN1 / IN2 input, the GRM-10 device avoids the status (it does not
	SK IN2 defining the level of the input IN1/IN2 that activates a specific output inputs is the high state HI. The low status is achieved by linking the selected in
to terminal C. <on off=""> A parameter for the RELAY1/RELAY2 keyw</on>	
ON - the output is on. OFF - the output is off. <t1> Time [s] of the OUT1 / OUT2 output after a</t1>	defined status occurred in IN1 input. This parameter is configured in the range
1 to 3600.	
1 to 3600.	defined status occurred in IN1 input. This parameter is configured in the range
	than inputs. It means that if a specific status occurs in IN1/IN2 inputs, the OL 1>/ <t2> time. It can be switched off by means of a CLIP or a TEXT MESSA</t2>
In case of MEM parameter adjustment (in RELAY1 / REL for inputs in the time mode is the status before activation	AY2 configuration commands) for a selected output, the adjustment remembe n of the <t1>/<t2>.</t2></t1>
TASK IN1 <lo hi=""> NONE M</lo>	ESSAGE <text 30="" content="" message="" signs="" to="" up=""></text>
TASK IN2 <lo hi=""> NONE M</lo>	ESSAGE <text 30="" content="" message="" signs="" to="" up=""></text>
are configured in the INFO command. The text message configured in the INFO command. The text message configured in the input results in sending a text message configured in the input results in sending a text message configured in the input results in sending a text message configured in the input results in sending a text message configured in the input results	tent to be sent by the GRM-10 device to its receivers. Their telephone numbers telephone numbers telephone numbers telephone as a specific status < stage.
TASK INx <lo hi=""> RELAYx <on off="" th="" ti<=""><th>ME> <tx> MESSAGE <text 30="" content="" message="" signs="" to="" up=""></text></tx></th></on></lo>	ME> <tx> MESSAGE <text 30="" content="" message="" signs="" to="" up=""></text></tx>
The command makes the connection between the spec of the OUT1 / OUT2 output and sending a text message X number of an input / output 1 input /output IN1/OUT1	ific status occurrence (LO/HI) in the IN1/IN2 input with an appropriate actival (MESSAGE) with a defined content
2 input /output IN2/OUT2 <tx> f the output must be active for a period of time (TIM</tx>	IE) than the personator defines time for the time made. This personator is see
ured in the range of 1 to 3600.	ic), then the parameter defines time for the time mode. This parameter is con
-	
Examples of commands: Command	Description
Examples of commands: Command TASK IN1 LO RELAY1 ON	Description After LO status appears in IN1 input, the OUT1 output switches on.
Examples of commands: Command	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off.
Examples of commands: Command TASK IN1 LO RELAY1 ON	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10 TASK IN1 LO NONE	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec. After LO status appears in IN1 input, no GRM-10 reaction. After HI status appears in IN2 input, no GRM-10 reaction.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10 TASK IN1 LO NONE TASK IN1 LO NONE TASK IN1 LO NONE MESSAGE WODA W POMIESZCZENIU TASK IN1 HI NONE MESSAGE WODA WYPOMPOWANA	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec. After LO status appears in IN1 input, no GRM-10 reaction. After HI status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN1 input, no GRM-10 reaction. After LO status appears in IN1 input, the "WODA W POMIESZCZENIU" m sage is sent. After HI status appears in IN1 input, only the "WODA WYPOMPOWAI message is sent.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10 TASK IN1 LO NONE TASK IN1 LO NONE TASK IN1 LO NONE MESSAGE WODA W POMIESZCZENIU TASK IN1 HI NONE MESSAGE WODA WYPOMPOWANA TASK IN1 LO RELAY1 ON MESSAGE STAN NISKI NA IN1	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec. After LO status appears in IN1 input, no GRM-10 reaction. After HI status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN1 input, the "WODA W POMIESZCZENIU" m sage is sent. After HI status appears in IN1 input, only the "WODA WYPOMPOWAI message is sent. After LO status appears in IN1 input, the OUT1 output switches on and a message "STAN NISKI NA IN1" is sent.
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10 TASK IN1 LO NONE TASK IN1 LO NONE TASK IN1 LO NONE MESSAGE WODA W POMIESZCZENIU TASK IN1 HI NONE MESSAGE WODA WYPOMPOWANA TASK IN1 LO RELAY1 ON MESSAGE	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec. After LO status appears in IN1 input, no GRM-10 reaction. After HI status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN1 input, no GRM-10 reaction. After LO status appears in IN1 input, the "WODA W POMIESZCZENIU" m sage is sent. After HI status appears in IN1 input, only the "WODA WYPOMPOWAI message is sent. After LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appears in IN1 input, the OUT1 output switches on and a filter LO status appeares in IN1 input, the OUT1 output switches on and a fil
Examples of commands: Command TASK IN1 LO RELAY1 ON TASK IN1 LO RELAY1 ON TASK IN1 HI RELAY2 OFF TASK IN2 LO RELAY1 TIME 30 TASK IN1 HI RELAY2 TIME 10 TASK IN1 HI RELAY2 TIME 10 TASK IN1 LO NONE TASK IN1 LO NONE MESSAGE WODA W POMIESZCZENIU TASK IN1 HI NONE MESSAGE WODA WYPOMPOWANA TASK IN1 LO RELAY1 ON MESSAGE STAN NISKI NA IN1 TASK IN2 LO RELAY2 TIME 60 MESSAGE	Description After LO status appears in IN1 input, the OUT1 output switches on. After HI status appears in IN2 input, the OUT2 output switches off. After LO status appears in IN2 input, the OUT1 output status changes 30 sec. After HI status appears in IN1 input, the OUT2 output status changes for sec. After LO status appears in IN1 input, no GRM-10 reaction. After HI status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN2 input, no GRM-10 reaction. After LO status appears in IN1 input, the "WODA W POMIESZCZENIU" m sage is sent. After HI status appears in IN1 input, only the "WODA WYPOMPOWAI message is sent. After LO status appears in IN1 input, the OUT1 output switches on and a message "STAN NISKI NA IN1" is sent. After LO status appears in IN2 input, the OUT2 output changes for time to status appears in IN2 input, the OUT3 output switches on and a message sent.

ther devices e by ti any th ird pa needed for the product functioning, d) damage caused by Act of God or any other incidents independent of the manufacturer - ZAMEL Sp z o.o. a) power source (batteries) in the device during sale (if any).
b) The PURCHASER shall lay any claims in writing to the dealer or ZAMEL Sp. z o.o.
c) ZAMEL Sp. z o.o. is liable for processing any claim according to current Polish legislation.
ZAMEL Sp. z o.o. shall process the claim at its own discretion: product repair, replacement or money return. The manufacturer's guarantee is valid in the Republic of Poland. The PURCHASER's statutory rights in any applicable legislation whether against the retailer arising from the purchase contract or Salesman stamp and signature, date of sale otherwise are not affected by this warranty.

EF COMMAND

he command allows to configure text messages used to control EXTA FREE system wireless receivers and selected LED lighting fittings and controllers of intelligent lighting Ledix series system. The control is possible only when the GRM-10 device is connected with the RXM-01 translator (www.extafree.pl) by means of RS-485 bus.

EF <address> <K1..Kn> <control text message content>

<address> This parameter defines the RXM-01 translator address on MODBUS bus that the specific control command refers to. This parameter is configured in the range of 1 to 247.

1 to 127). In one EF command up to 15 numbers of push-buttons can be configured. The push-buttons refer to a single control text message, for example in order to adjust several EXTA FREE system receivers by means of one text message.

<K1...Kn> The parameter defines the the number of push-buttons used to control EXTA FREE system receivers (possible numbers from <control text message content> The control command is adjusted by a user, the maximum number of signs is 32.

The user can define 127 independent control commands. The commands can not be repeated - if the command including a given content

already exists, the GRM-10 device will display ERROR as a response to this configuration text message. A similar message is given by the PC application. The control commands generated by the EF command are grouped in a table. Commands generated as text messages are placed at the end of the table and from a PC at the beginning. It should be helpful for the user to add new commands by means of a telephone. The maximum number of EF commands that can be configured is 127.

The EF commands table can be completely deleted by sending a EF RESET command in the configuration mode.

The user can configure the EF command in such a way as to adjust simultaneously several (up to 15) EXTA FREE / LEDIX system receivers, which are located within RXM-01 range. It is very important in creation the so called scenes or, for example, in the control of central roller blind drives. The next push-buttons codes are sent in a "one by one" sequence with an interval of 1 second.

The cooperation of GRM-10 device with RXM-01 device is fully described in the EXTA FREE CONTROL section by means of GSM.

Examples of commands

Command	
EF 1 K1 OSWIETLENIE ON	A text message with the content 'OS' 0x0,1 address to press a 0x0,1 push-
EF 1 K2 OSWIETLENIE OFF	A text message with the content 'OSV 0x0,1 address to press a 0x0,2 push-
EF 2 K3 SCHODY ON	A text message with the content 'SCH address to press a 0x0,3 push-button
EF 2 K4 SCHODY OFF	A text message with the content 'SCH address to press a 0x0,4 push-button
EF 1 K3 ROLETY GORA	A text message with the content 'ROL address to press a 0x0,3 push-button this code.
EF 1 K4 ROLETY DOL	A text message with the content 'ROI address to press a 0x0,4 push-butto this code.
EF 1 K1 K3 ALL ON (example of a stage)	A text message with the content 'AL blinds - it is equivalent to sending cod and 0x0,3 push-buttons.

OUTPUT CONTROL COMMANDS

0	Descrip
Command	Descrip
RELAY1 ON	Switch on OUT1 output
RELAY1 OFF	Switch off OUT1 output
RELAY2 ON	Switch on OUT2 output
RELAY2 OFF	Switch off OUT2 output
RELAY1 TIME	Change of OUT1 output status for time t1[s] adjust
RELAY2 TIME	Change of OUT2 output status for time t2[s] adjust
RELAY1 TIME <t></t>	Change of OUT1 output status for time <t> given justed in the range of 1 3600.</t>
RELAY2 TIME <t></t>	Change of OUT2 output status for time <t> given justed in the range of 1 3600.</t>
GATE	Output control in the gate mode. Switching on the and the OUT2 output for the default time <time gate mode, the pulse to close the gate is automati Times <time1>, <time2> and <time3> are adju</time3></time2></time1></time
GATE <t1> <t2></t2></t1>	Output control in the gate mode. Switching on the put for time <t2>. The <t1> parameter is adjusted is in the range of 0 360. If the AUTO parameter is the gate is automatically generated after time <t configuration.<="" during="" gate="" mode="" td="" the=""></t></t1></t2>
STATUS	Checking the output/input status (section: GRM-1
	ASS parameter (password to a text message) v bassword must be typed during the text message

Zamel RELAY1 ON; Zamel RELAY2 OFF; Zamel RELAY1 TIME 10; Zamel GATE; Zamel GATE 2 20

Description

WIETLENIE ON' - results in sending a code by RXM-01 with the -button. The result is that the receiver with this code is switched on. WIETLENIE OFF' - results in sending a code by RXM-01 with the button. The result is that the receiver with this code is switched off. HODY ON' – results in sending a code by RXM-01 with the 0x0,2 n. The result is that the receiver with this code is switched on. HODY OFF' – results in sending a code by RXM-01 with the 0x0,2 n. The result is that the receiver with this code is switched on. LETY GORA' - results in sending a code by RXM-01 with the 0x0,1 on. It results in opening the roller blind connected to SRP-02 with

DLETY DÓŁ' – results in sending a code by RXM-01 with the 0x0,1 on. It results in closing the roller blind connected to SRP-02 with

LL ON' - results in switching on the light and opening the roller des by RXM-01 with the 0x0,1 address to receivers to press 0x0,1

otion	Przykład
	-
	-
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sted during configuration	-
sted during configuration	-
in the control command. <t> parameter is ad-</t>	RELAY1 TIME 60
n in the control command. <t> parameter is ad-</t>	RELAY2 TIME 10
he OUT1 output for the default time <time1> 2>. If the AUTO parameter is adjusted for the ically generated after time <time3> is finished. usted during the gate mode configuration.</time3></time1>	-
e OUT1 output for time <t1> and the OUT2 out- in the range of 0 10 and the <t2> parameter s adjusted for the gate mode, the pulse to close TIME3> is finished. Time <time3> is adjusted</time3></t2></t1>	GATE 2 120
10 DEVICE REPLY TO STATUS COMMAND)	-
was adjusted during configuration in the Co ge control at the beginning.	ONFIG command

GRM-10 DEVICE REPLY TO STATUS COMMAND

A full GRM-10 device reply to STATUS command:

RELAY1 <ON/OFF - current OUT1 output status> TIME <Time left to measure for OUT1 output> RELAY2 <ON/OFF - current OUT2 output status> TIME <Time left to measure for OUT2 output> IN1 <LO/HI - current IN1 input status> IN2 <LO/HI - current IN2 input status>

Example:

RELAY1 ON TIME 30 RELAY2 OFF TIME 100 IN1 LO IN2 HI

If times for OUT1/OUT2 outputs are currently not measured, the reply to the STATUS command is: **RELAY1** <ON/OFF - current OUT1 status> **RELAY2** <ON/OFF - current OUT2 status> **IN1** <LO/HI - current IN1 status> **IN2** <LO/HI - current IN2 status>

or

RELAY1 <ON/OFF - current OUT1 status> **TIME** <0> RELAY2 <ON/OFF - current OUT2 status> TIME <0> **IN1** <LO/HI - current IN1 status> **IN2** <LO/HI - current IN2 status>

Example:

RELAY 1 ON RELAY 2 OFF IN1LO IN2HI

RELAY 1 ON TIME 0 RELAY 2 OFF TIME 0 IN1LO IN2HI

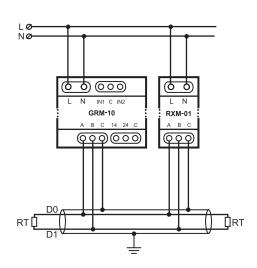
CONTROL OF EXTA FREE SYSEM RECEIVERS

The GRM-10 device, by receiving certain commands (text messages), can control the wireless EXTA FREE system receivers. It is necessary to connect the GRM-10 device with RXM-01 translator using the RS-485 interface. The GRM-10 device has such a default setting that allows for a direct cooperation with RXM-01. If the transmission parameters change is necessary (standard, transmission rate, parity) between GRM-10 and RXM-01 use the **MODBUSCONFIG** command.

CAUTION: The transmission line between the GRM-10 device and the RXM-01 device is a two-wire shielded twisted-pair cable (it is recommended to earth in a single point the shield line). The resistors (terminators) of 120 Ohm should be placed at the beginning and at the end of the line.

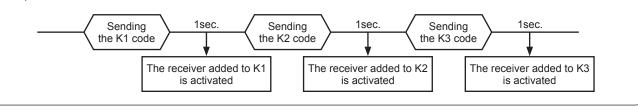
he following points should also be carried out:

- Connect the RXM-01 device to a PC. An appropriate "adapter" RS232 -RS485 or USB - 485 (depending on the computers' output) should be used.
- 2. Using the PC application that is dedicated to configure the GRM-10 device, particular control commands and responding number of push-buttons shall be defined in the EXTA fREE section. For each command, specify The RXM-01 address for the MODBUS bus should be defined. The default address is 0x01. The address is important for a larger number of RXM-01 operating independently on a single object.
- Following the description of the PC, add (programme) particular push-buttons sent by the RXM-01 device to appropriate EXTA FREE system receivers.
- After programming the receivers, use the PC application to check their appropriateness.
- 5. Adjust the GRM-10 device into a normal operation mode and check the operation by sending defined control commands to the GRM-10 device (the proper communication between RXM-01 and GRM-10 after sending a control command is indicated by the LED diode RS485, it switches on).



If in the EXTA FREE control command several push-buttons are defined, the codes are sent to RXM-01 device with a defined address in a sequence one after another and with an interval of 1 sec.

Example: EF K1 K2 K3 SALON OFF



REMARKS

- Due to the queuing (prioritisation) of text messages in the GSM network, some delays related to sending the control command and its realisation are possible (for example the adjustment of the GRM-10 outputs or EXTA FREE receivers). The delays can be from several to tens o seconds.
- Due to the representation of the text message content, the configuration and control of the GRM-10 device is not possible by means of "SMS gateways" that are provided by the GSM operators.
- In case of operators using other resources of the GSM network, it is not possible to choose the operator manually. The logging
 procedure is automatical the operator with the strongest signal is chosen. Successful login of the GRM-10 device to the GSM
 network is indicated by a flashing LED GSM STATUS diode with a frequency of 1/s. Make sure that the device is mounted in
 areas with the GSM network reception. Operation on the reception border can have a negative influence on a proper operation
 of the GRM-10 device and other devices in cooperation.
- It is important to switch off the PIN code or adjust the code to 1111 before installing the SIM card in the GRM-10 device.
- It is recommended to switch of the VOICEMAIL service on the card installed in the GRM-10 DEVICE.